



NEW arc welding robot ARC Mate 100iD

It's the first of a new generation: with its sophisticated slim, curved design and fully integrated welding hosepack and utility cables, the brand new FANUC ARC Mate 100*i*D offers new possibilities for improved productivity and faster integration. A larger workspace, reach and stroke, even in the backflip area, allows for a bigger working range. Improved rigidity and repeatability together with faster motion speed, mean increased productivity.

ARC Mate 100iD





	J6 Moment/ Inertia (Nm/kgm²)	11.0/0.30
	J5 Moment/ Inertia (Nm/kgm²)	26.0/0.90
	J4 Moment/ Inertia (Nm/kgm²)	26.0/0.90
	96	720
(s)	75	260 430 450 720
/aximum speed (°/s)	74	430
ximum	513	260
Ma	72	240
	17	260
	97	006
_	75	380
Motion range (°)	J4	380
Motion	73	235 450
	72	235
	L L	340 (370)
	Mechanical weight (kg)	145
	Repeatability (mm)	± 0.02*
	Controlled axes	9

B Robo	Moun	Open Mate A-cak	iPenc Elect Volta Avera	Integ Integ Integ	Envir Acou	Prote Body Wrist	
		0° 0 0° 0 0° 0 0° 0 0° 0 0° 0 0° 0 0°	(475, +1816) J5 axis rotation center		Motion range of the J5 axis rotation center	(0,0)	(+422, -800)
Working range	170°	(-185°) (185°) (-170°) (-170°)			[-1291, +450]		Motion range may be restricted according to the mounting angle!

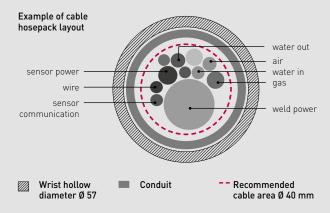
⊟ Kobot	ARC Mate 1007D
Robot footprint [mm]	343 x 343
Mounting position Floor	•
Mounting position Upside down	•
Mounting position Angle	•
oon Controller	R30iB Plus
Open air cabinet	1
Mate cabinet	0
A-cabinet	•
B-cabinet	0
<i>i</i> Pendant Touch	•
Electrical connections	
Voltage 50/60Hz 3phase [V]	380-575
Voltage 50/60Hz 1phase [V]	1
Average power consumption [kW]	1
Integrated services	
ntegrated signals on upper arm In/Out	1/1
ntegrated air supply	1
Environment	
Acoustic noise level [dB]	< 70
Ambient temperature [° C]	0-45
Protection	
Body standard/optional	IP54
Wrist & J3 arm standard/optional	L7GI

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Fully integrated welding hosepack and cable management

- easy routing of the welding dressout and seam tracking sensors cables throughout the robot
- eliminates robot interference with peripherals and work cell equipment
- various dressout configurations suitable for each application
- quickly retrofittable including routing sensor/tooling cables into J3 arm
- improved system reliability and ease of use



Largest hollow wrist in its class (57mm)

- to allow routing torch hosepack as well as additional utilities such as seam tracking sensor cables, vision cables, or air pipes
- compact and fully articulated to reach narrow spaces in jigs and tight fixtures
- shorter J5 offset for high accuracy motion
- smooth appearance with minimum fastener bolts exposed, reducing spatter collection



Largest J1 hollow reducer (108 mm)

- easy routing of welding dressouts, third party supplies and sensor cables from robot flange through axis 1
- allowing the design of more compact welding cells with less interference with peripheral equipment



Easy maintenance

Smooth surfaces keep dirt and spatter build-up to a bare minimum, making it easy to maintain the robot and welding utilities.



Easy to use and quick to install Seamless integration with welding equipment packages save installation time and cost